

# Some Properties of Force Fields on the Groups of Diffeomorphisms of the flat $n$ -Dimensional Torus, connected with the Notion of Parallelism

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## **Abstract**

Some existence of solution theorems are proved for second order differential inclusions on the groups of diffeomorphisms of a flat  $n$ -dimensional torus. The technical tool for the proofs is the use of the notion of parallelism on those groups.

**Key words:** Flat torus; groups of diffeomorphisms; differential inclusions; parallelism

## **1 Introduction and preliminaries**

We investigate second order differential equations and inclusions on the group  $D^s(\mathcal{T}^n)$  of Sobolev  $H^s$ -diffeomorphisms of flat  $n$ -dimensional torus  $\mathcal{T}^n$ ,  $s > \frac{n}{2} + 1$ . The necessary preliminaries on their group and Hilbert manifold structures can be found in [2, 4].

Besides the group structure mentioned above, on  $D^s(\mathcal{T}^n)$  there exists an additional structure generated by the global parallelism of the tangent bundle on  $\mathcal{T}^n$ . This structure is the main technical tool of our consideration. It is described as follows (see, e.g., [4]).

**Definition 1.** Introduce the operators:

- (i)  $B : T\mathcal{T}^n \rightarrow \mathbb{R}^n$ , the projection to the second factor in  $T\mathcal{T}^n = \mathcal{T}^n \times \mathbb{R}^n$ ;
- (ii)  $A(m) : \mathbb{R}^n \rightarrow T_m\mathcal{T}^n$ , the inverse to  $B$  (see (i)) mapping to the tangent space to  $\mathcal{T}^n$  at  $m \in \mathcal{T}^n$ ;
- (iii)  $Q_g = A(g(m)) \circ B$ , a linear isomorphism  $Q_g : T_m\mathcal{T}^n \rightarrow T_{g(m)}\mathcal{T}^n$ , where  $g \in D^s$  and  $m \in \mathcal{T}^n$ .

The operator  $Q_e$  is a one, different from the right shift, that sends every tangent space to the group isomorphically to the tangent space at the unit  $e$ . Thus, besides the right-invariant vector fields on  $D^s(\mathcal{T}^n)$  there is another class of fields with a property of invariance, this time with respect to the action of operator  $Q$ . We call these fields parallel.

**Definition 2.** A vector field  $X$  on  $D^s(\mathcal{T}^n)$  is called parallel if at every point  $\eta \in D^s(\mathcal{T}^n)$  its value  $X_\eta = Q_\eta X_e$  where  $X_e \in T_e D^s(\mathcal{T}^n)$ .

Note that the parallel vector field  $X$  is invariant with respect to  $Q_\theta$  for every  $\theta \in D^s(\mathcal{T}^n)$ .

By  $i$  we denote an isometric embedding of  $\mathcal{T}^n$  to a Euclidean space  $\mathbb{R}^k$  for  $k$  large enough, that exists by well-known Nash's theorem.

This embedding  $i : \mathcal{T}^n \rightarrow \mathbb{R}^k$  generates the embedding of  $D^s(\mathcal{T}^n)$  to the Hilbert space  $H^s(\mathcal{T}^n, \mathbb{R}^k)$ , which we denote by the same symbol  $i$ .

Recall that a tubular neighborhood  $U$  of the submanifold  $iD^s(\mathcal{T}^n)$  in  $H^s(\mathcal{T}^n, \mathbb{R}^k)$  has the structure of direct product  $U = iD^s(\mathcal{T}^n) \times W$ , where  $W$  is a ball in the space normal to the tangent space  $T_e D^s(\mathcal{T}^n)$ ,  $e = id$  is the unit in the group  $D^s(\mathcal{T}^n)$ . By  $r$  we denote the retraction  $r : U \rightarrow D^s(\mathcal{T}^n)$ . Thus the tangent spaces to  $U$  are represented as  $T_\xi U = T_{r\xi} D^s(\mathcal{T}^n) \times T_\xi W$ . If  $X(\eta)$  is a vector field on  $D^s(\mathcal{T}^n)$ , the tangent map  $Ti$  sends it into the vector field  $TiX$  on  $iD^s(\mathcal{T}^n)$ . By symbol  $\bar{X}$  we denote the extension of  $TiX$  to  $U$  of the form  $\bar{X}_\xi = (TiX_{r\xi}, 0)$ .

On  $D^s(\mathcal{T}^n)$  one can introduce a strong Riemannian metric, say, as in [2, 4]. By  $dist(\eta, \theta)$  we denote the Riemannian distance between  $\eta$  and  $\theta$  (i.e., the infimum of curve lengths for curves joining  $\eta$  and  $\theta$ ). Introduce on  $TD^s(\mathcal{T}^n)$  the distance  $d$  by the formula

$$d((X(\eta)), (Y(\theta))) = dist(\eta, \theta) + \|Q_e X(\eta) - Q_e Y(\theta)\|, \quad (1.1)$$

where the norm in  $T_e D^s(\mathcal{T}^n)$  is generated by the strong Riemannian metric. Besides, we shall use the distance between the above-mentioned vectors in  $\mathbb{R}^k$  after embedding. This distance is denoted by  $\|iX(\eta) - iY(\theta)\|$ .

Introduce another strong Riemannian metric on  $TD_\mu^s(\mathcal{T}^n)$  as follows (see [3]). Represent the tangent space  $T_{(m,X)} TD_\mu^s(\mathcal{T}^n)$  as the direct product of the vertical subspace  $\bar{V}_{(m,X)}$  and the space of Live-Civita connection  $\bar{H}_{(m,X)}$  of the weak Riemannian metric (see [2]) on  $D_\mu^s(\mathcal{T}^n)$ . For every  $U$  and  $V$

from  $\bar{V}_{(m,X)}$  define the inner product as  $(KU, KV)_\eta^s$  where  $K$  is the connector of the above-mentioned Levi-Civita connection and  $(\cdot, \cdot)_\eta^s$  is the strong inner product in  $T_\eta D^s(\mathcal{T}^n)$  generated by the strong Riemannian metric. For every  $X$  and  $Y$  from  $\bar{H}_{(m,X)}$  define the inner product as  $(T\pi X, T\pi Y)_\eta^s$ . Set  $\bar{H}_{(m,X)}$  and  $\bar{V}_{(m,X)}$  to be orthogonal to each other. Thus, on  $TD_\mu^s(\mathcal{T}^n)$  a certain strong Riemannian metric is well-defined. The Riemannian distance, i.e., the infimum of the length of curves, connecting the points in  $TD^s$ , with respect to the above Riemannian metric, is denoted by  $d_1$ .

Construct the distance  $d_2(X, Y)$  on  $TTD_\mu^s(\mathcal{T}^n)$ , analogous to the distance  $d$  on  $TD_\mu^s(\mathcal{T}^n)$ , by the formula

$$\begin{aligned} d_2(X, Y) = & d(\pi_1 X, \pi_1 Y) + \|Q_e K X_v - Q_e K Y_v\| \\ & + \|Q_e T\pi X_h - Q_e T\pi Y_h\|, \end{aligned} \quad (1.2)$$

where  $\pi : TD_\mu^s(M) \rightarrow D_\mu^s(M)$  is the natural projection,  $X_v$  and  $Y_v$  are the vertical components of  $X$  and  $Y$  while  $X_h$  and  $Y_h$  are their horizontal components.

For the metrics  $dist$ ,  $d$ ,  $d_1$  and  $d_2$  and for the norm  $\|\cdot\|$  in  $T_e D^s(\mathcal{T}^n)$  we shall consider their Kuratowski measures of non-compactness which will be denoted by  $\alpha_{dist}$ ,  $\alpha_d$ ,  $\alpha_{d_1}$ ,  $\alpha_{d_2}$  and  $\alpha_{\|\cdot\|}$ , respectively. We refer the reader, say, to [1], where the definitions of measures of non-compactness and of condensing operators are given and the corresponding theory is described in details.

We say that a force field  $F(t, m, X)$  is given on a manifold  $M$  if in the tangent space  $T_m M$  at every  $m \in M$  a certain vector  $F(t, m, X)$  depending on the time  $t$  and the vector  $X \in T_m M$ , is given. The force fields are right-hand sides of the second order differential equations on manifolds given in terms of covariant derivatives (see, e.g., [4]).

The main aim of the paper is investigation of set-valued force fields and the corresponding second order differential inclusions on the groups of diffeomorphisms of the flat  $n$ -dimensional torus with the use of the notion of parallelism. On this base some existence of solution theorems for second order differential inclusions on the above-mentioned groups are obtained.

The definitions and principal facts from the theory of set-valued maps and differential inclusions are contained in [6].

## 2 Second order differential inclusions

**Lemma 1.** *Let a set-valued force field  $F : [0, l] \times TD^s(\mathcal{T}^n) \rightarrow TD^s(\mathcal{T}^n)$  with convex values satisfy the upper Caratheodory condition and be such that for almost all  $t$  for the mapping  $A : [0, l] \times TD^s(\mathcal{T}^n) \rightarrow T_e D^s(\mathcal{T}^n)$  of the form  $A(t, \eta, X) = Q_e F(t, \eta, X)$  and for every bounded set  $\Omega \subset D^s(\mathcal{T}^n)$  the inequality  $\alpha_{\|\cdot\|}(A(t, \Omega)) \leq g(t) \alpha_d(\Omega)$  holds. Then for almost all  $t$  the vector*

field  $F(t, \eta, X)$  is  $k$ -bounded with respect the measure of non-compactness  $\alpha_d$  with the coefficient  $1 + g(t)$ .

**Proof.** By the hypothesis for every  $\Omega \subset TD^s$ , for which  $\alpha_d(\Omega)$  is finite, the inequality  $\alpha_{\|\cdot\|}(A(t, \Omega)) \leq g(t) \alpha_d(\Omega)$  holds. Specify  $t \in [0, l]$ . Suppose that  $\alpha_d(\Omega) = \xi$ , i.e., for every  $\varepsilon > 0$  there exists a finite cover of  $\Omega$  by the sets  $\Theta_i$  with diameters  $\xi + \frac{\varepsilon}{2}$ . Then from the hypothesis it follows that there exists a finite cover of  $A(t, \Omega) \subset T_e D^s(\mathcal{T}^n)$  by the sets  $G_j$  with diameters  $g(t) \xi + \frac{\varepsilon}{2}$ . Consider the set  $Q_\eta A(t, \Omega) \subset T_\eta D^s(\mathcal{T}^n)$ . Then the set  $\bigcup_{\eta \in \Omega} Q_\eta A(t, \Omega)$  has the natural structure of direct product  $\Omega \times A(t, \Omega)$ . Consider the set  $G_{ij} = \bigcup_{\eta \in \Theta_i} Q_\eta G_j$ . The collection of sets  $G_{ij}$  forms a finite cover of  $\Gamma$  and the diameter of every such set with respect to the distance  $d$  is not greater then  $\xi + g(t) \xi + \varepsilon$ . Hence  $\alpha_d(\Gamma) \leq (1 + g(t)) \xi$ . Since  $F(t, \Omega) \subset \Gamma$ , for almost all  $t$  the vector field  $F(t, \eta, X)$  is  $k$ -bounded with respect to the measure of non-compactness  $\alpha_d$  with the coefficient  $1 + g(t)$ .  $\square$

**Lemma 2.** *Let the set-valued force field  $F$  on  $TD^s(\mathcal{T}^n)$  is as in the previous Lemma. Then the vertical lift of this mapping*

$$F^l : [0, l] \times TD^s(\mathcal{T}^n) \rightarrow TTD^s(\mathcal{T}^n)$$

*is  $k$ -bounded with respect to the measures of non-pcompactness  $\alpha_d$  and  $\alpha_{d_2}$  with the coefficient  $2 + g(t)$ .*

**Proof.** Specify  $t \in [0, l]$ . Consider the set  $\Theta \subset TD^s(\mathcal{T}^n)$ . Let its measure of non-compactness  $\alpha_d(\Theta) = \xi$ . This means that for every  $\varepsilon > 0$  it can be covered by a finite number of sets  $\Theta_i$  with diameter  $\xi + \varepsilon$ . Then from the definition of distance  $d$  it follows that the set  $\pi\Theta$  can be covered by a finite number of sets  $\pi\Theta_i$  whose diameter is not greater than  $\xi + \varepsilon$ , i.e.,  $\alpha_d(\pi\Theta) \leq \xi$ . Then by the hypothesis  $\alpha_{\|\cdot\|}(A(t, \pi\Theta)) \leq g(t) \xi$ , i.e.,  $(A(t, \pi\Theta)) \subset T_e D^s(\mathcal{T}^n)$  can be covered by a finite number of sets  $G_j$  with the diameter nit greater than  $g(t) \xi + \varepsilon$ . By analogy with the proof of the previous Lemma consider the sets  $G_{ij}^l = \bigcup_{\theta \in \Theta_i} (Q_{\pi\theta} G_j)^l$ . It is evident that the collection of all  $G_{ij}^l$  covers the image  $F^l(t, \Theta)$ . Since we have the finite number of those sets and the diameter of each one is not greater than  $2\xi + g(t)\xi + \varepsilon$ , the Lemma follows.  $\square$

Introduce the norm  $\| \| F^l \| \| = \sup_{y \in F^l} \| \| y \| \|$ . Choose an arbitrary point  $Z \in TD^s(\mathcal{T}^n)$ . Since at every given  $t$  the set-valued map  $F^l$  is upper semicontinuous, there exists a neighborhood  $V'(Z) \subset TD^s(\mathcal{T}^n)$  of the point  $Z$  such that for  $Y \in V'(Z)$  the relation  $\| \| F^l(t, Y) \| \| < \| \| F^l(t, Z) \| \| + C$  holds.

Determine the neighborhood  $\tilde{V}(Z) \subset TD^s(\mathcal{T}^n)$  by the formula  $\tilde{V} = V \cap V'$  where  $V$  is the neighborhood from [3, Theorem 1]. Specify a neighborhood

$D \subset U$  of  $Z$  as in [5, Theorem 1.4] such that  $r(D) \subset \tilde{V}$ . By [5, Theorem 1.4] the retraction  $r$  is Lipschitz continuous on  $D$  with the constant 2.

**Theorem 3.** *On the domain  $D$  for almost all  $t$  the vector field  $\bar{F}^l$  is  $k$ -bounded with respect to the measure of non-compactness  $\alpha_{\|\cdot\|}$  with the coefficient*

$$2(2 + g(t)) (1 + a + k(C + \|\|F^l(t, Z)\|\|)).$$

**Proof.** Consider the set  $\Omega \subset D$ . Let  $\alpha(\Omega) = \xi$ . I.e., for every  $\varepsilon > 0$  it can be covered by a finite number of sets  $\Omega_i$  with diameter non greater than  $\xi + \varepsilon$ . Consider the set  $r(\Omega) \subset TD^s(\mathcal{T}^n)$ , where  $r$  the retraction mentioned above. By [5, Theorem 1.4] the retraction  $r$  is Lipschitz continuous on  $D$  with the constant 2 with respect to the norm  $\|\cdot\|$  on  $D$  and the distance  $d_1$  on  $TD^s(\mathcal{T}^n)$ . Hence the set  $r(\Omega)$  can be covered by a finite number of the sets with diameter not greater than  $2\xi + \varepsilon$  with respect to  $d_1$ . Consider the set  $F^l(t, r(\Omega)) \subset TTD^s(\mathcal{T}^n)$ . This set can be covered by a finite number of sets with diameter not greater than  $2(2 + g(t))\xi + \varepsilon$  with respect to the distance  $d_2$ . Now from Lemma 2 and from the construction of the neighborhoods  $\tilde{V}$  and of  $D$  it follows that the set  $\bar{F}^l(t, \Omega)$  can be covered by a finite number of sets with diameter not greater than  $2(2 + g(t))(1 + a + k(C + \|\|F^l(t, Z)\|\|))\xi + \varepsilon$ . Hence  $\bar{F}^l$  is condensing on  $D$  with respect to  $\alpha_{\|\cdot\|}$  with the coefficient

$$2(2 + g(t)) (1 + a + k(C + \|\|F^l(t, Z)\|\|)). \quad \square$$

Let  $F$  be a set-valued force field with convex images on  $TD^s(\mathcal{T}^n)$  that satisfies the upper Caratheodory condition. Consider the differential inclusion

$$\frac{\tilde{D}}{dt}\dot{\eta}(t) \in F(t, \eta, \dot{\eta}). \quad (2.1)$$

This problem is reduced to the differential inclusion  $\dot{\eta} \in \tilde{S} + F^l$  on  $TD^s(\mathcal{T}^n)$  where  $F^l$  is the vertical lift of  $F$  TO  $D^s(\mathcal{T}^n)$  and  $\tilde{S}$  is the geodesic spray of the Levi-Civita connection of the weak metrics. It is known that  $\tilde{S}$  is smooth and satisfies the condition  $T_\pi\tilde{S}(X) = X$ . Consider the extension  $\bar{S} : U \rightarrow U$  of  $\tilde{S} : TD^s(\mathcal{T}^n) \rightarrow TTD^s(\mathcal{T}^n)$  defined by the formula  $\bar{S}(x) = TjS(r(x))$ ,  $x \in U$ .

**Theorem 4.** *Let the set-valued force field  $F : [0, l] \times TD^s(\mathcal{T}^n) \rightarrow TD^s(\mathcal{T}^n)$  with convex images satisfy the upper Caratheodory condition and be such that for almost all  $t$  the map  $A : [0, l] \times TD^s(\mathcal{T}^n) \rightarrow T_eD^s(\mathcal{T}^n)$  of the form  $A(t, X) = Q_eF(t, X)$  is  $k$ -bounded with respect to the measures of non-compactness  $\alpha_d$  and  $\alpha_{\|\cdot\|}$  with the coefficient  $g(t)$ . Then for almost all  $t$  the vector field  $\bar{S} + \bar{F}^l$  is locally  $k$ -bounded on a small enough neighborhood  $U$  in  $TD^s(\mathcal{T}^n)$  with respect to the measures of non-compactness  $\alpha_{\|\cdot\|}$ .*

**Proof.** By Theorem 3 for almost all  $t \in [0, l]$  for every  $Z \in TD^s(\mathcal{T}^n)$  there exists its neighborhood  $D$  in  $U$ , on which the set-valued force field  $\bar{F}^l$  is  $k$ -bounded with the coefficient  $k = 2(2 + g(t))(1 + a + k(C + \|\|F^l(t, Z)\|\|))$  relative to the measure of non-compactness  $\alpha_{\|\cdot\|}$ . The geodesic spray  $\tilde{S}$  is a  $C^\infty$ -smooth vector field. The embedding  $j$  and the retraction  $r$  are  $S^\infty$ -smooth as well. Thus the vector field  $\bar{S}$  on  $U$  is  $C^\infty$  smooth and so, in particular, locally Lipschitz continuous. Hence on a small enough neighborhood of the point  $Z$  the field  $\bar{S}$  is Lipschitz continuous with a certain constant  $g > 0$ . Without loss of generality one can suppose that  $D$  is the above-mentioned neighborhood. By the properties of Kuratowski's measure of non-compactness the sum of locally  $k$ -bounded and a locally Lipschitz continuous field is locally  $k$ -bounded. Hence the set-valued vector field  $\bar{S} + \bar{F}^l$  is locally  $k$ -bounded with respect to the measure of non-compactness  $\alpha_{\|\cdot\|}$  with the coefficient  $k = 2(2 + g(t))(1 + a + k(C + \|\|F^l(t, Z)\|\|)) + g$ .  $\square$

**Theorem 5.** *Let the hypothesis of Theorem 4 are fulfilled and the function  $g(t)$  be square integrable on the interval  $[0, T]$ . Specify a point  $Z_0 \in TD^s(\mathcal{T}^n)$ . Suppose that on the closure  $\bar{D}$  of a certain neighborhood  $D$  of this point the estimate  $\|F(t, X)\| < f(t)$ ,  $X \in \bar{D}$  holds, where  $f(t) > 0$  is a real function that is square integrable on  $[0, l]$ . Then the initial value problem (2.1) with initial condition  $\eta(0) = \pi Z_0, \dot{\eta}(0) = Z_0$  has a local solution.*

**Proof.** Without loss of generality one can consider  $D$  as a neighborhood from the proof of Theorem 4. Consider the initial value problem  $\gamma'(t) \in \bar{S} + \bar{F}^l$  on  $U$  with the initial condition  $\gamma(0) \in Z_0 \in jT_e D^s(\mathcal{T}^n)$ . Under the hypothesis, the function

$$k(t) = 2(2 + g(t))(1 + a + k(C + \|\|F^l(t, Z)\|\|)) + g$$

is integrable on  $[0, l]$ . Then from Theorem 4 it follows that the right-hand side of the latter differential inclusion satisfies the conditions of [6, Theorem 5.2.1] and so this initial value problem has a local solution. By analogy with [5, Theorem 2.4] one can easily prove that this solution belongs to  $jTD^s(\mathcal{T}^n)$ . Inclusion (2.1) is reduced to the inclusion with right-hand side  $\tilde{S} + F^l$ . This means that  $\pi\gamma(t)$  satisfies inclusion (2.1).  $\square$

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